

ATV930U75N4

variable speed drive - ATV930 - 7,5kW -
400/480V - with braking unit - IP21



Main

| | |
|------------------------------------|---|
| Range of product | Altivar Process ATV900 |
| Product or component type | Variable speed drive |
| Device application | Industrial application |
| Device short name | ATV930 |
| Variant | Standard version |
| Product destination | Asynchronous motors Synchronous motors |
| Mounting mode | Wall mount |
| EMC filter | Integrated conforming to EN/IEC 61800-3 category C3 with 150 m motor cable maxi Integrated conforming to EN/IEC 61800-3 category C2 with 50 m motor cable maxi |
| IP degree of protection | IP21 conforming to IEC 60529 IP21 conforming to IEC 61800-5-1 |
| Degree of protection | UL type 1 conforming to UL 508C |
| Type of cooling | Forced convection |
| Supply frequency | 50...60 Hz (+/- 5 %) |
| Network number of phases | 3 phases |
| [Us] rated supply voltage | 380...480 V (- 15...10 %) |
| Motor power kW | 5.5 kW (heavy duty) 7.5 kW (normal duty) |
| Motor power hp | 7.5 hp (heavy duty) 10 hp (normal duty) |
| Line current | 9.2 A at 480 V (heavy duty) 10.5 A at 380 V (heavy duty) 11.9 A at 480 V (normal duty) 13.8 A at 380 V (normal duty) |
| Prospective line I _{sc} | 50 kA |
| Apparent power | 7.6 kVA at 480 V (heavy duty) 9.9 kVA at 480 V (normal duty) |
| Continuous output current | 12.7 A at 4 kHz (heavy duty) 16.5 A at 4 kHz (normal duty) |
| Maximum transient current | 19.1 A during 60 s (heavy duty) 19.8 A during 60 s (normal duty) |
| Asynchronous motor control profile | Constant torque standard Variable torque standard Optimized torque mode |
| Synchronous motor control profile | Permanent magnet motor |
| Speed drive output frequency | 0.1...500 Hz |
| Nominal switching frequency | 4 kHz |
| Switching frequency | 4...16 kHz with derating factor 2...16 kHz adjustable |
| Safety function | STO (safe torque off) SIL 3 |
| Number of preset speeds | 16 preset speeds |

The information provided in this documentation contains general descriptions and/or technical characteristics of the performance of the products contained herein. This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications. It is the duty of any such user or integrator to perform the appropriate and complete risk analysis, evaluation and testing of the products with respect to the relevant specific application or use thereof. Neither Schneider Electric Industries SAS nor any of its affiliates or subsidiaries shall be responsible or liable for misuse of the information contained herein.

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| Communication port protocol | Modbus serial Modbus TCP Ethernet IP |
| Option module | Slot B: resolver encoder interface module Slot B: analog encoder interface module Slot B: 5/12 V digital encoder interface module Slot A/slot B/slot C: output relay extension module Slot A/slot B/slot C: digital and analog I/O extension module Slot A: communication module for CANopen screw terminals Slot A: communication module for CANopen SUB-D 9 Slot A: communication module for CANopen daisy chain RJ45 Slot A: communication module for EtherCAT Slot A: communication module for DeviceNet Slot A: communication module for Profinet Slot A: communication module for Profibus DP V1 |

Complementary

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|-------------------------------------|--|
| Output voltage | \leq power supply voltage |
| Motor slip compensation | Adjustable Automatic whatever the load Can be suppressed Not available in permanent magnet motor law |
| Acceleration and deceleration ramps | Linear adjustable separately from 0.01 to 9000 s S, U or customized |
| Braking to standstill | By DC injection |
| Protection type | Drive: break on the control circuit Drive: overspeed Drive: line supply phase loss Drive: line supply undervoltage Drive: line supply overvoltage Drive: overvoltages on the DC bus Drive: motor phase break Drive: short-circuit protection Drive: overload of output voltage Drive: overcurrent between output phases and earth Drive: overheating Drive: safe torque off Drive: thermal protection Motor: motor phase break Motor: safe torque off Motor: thermal protection |
| Frequency resolution | Analog input: 0.012/50 Hz Display unit: 0.1 Hz |
| Electrical connection | DC bus, screw terminal: 4...6 mm ² (AWG 12...AWG 10) Motor, screw terminal: 6...10 mm ² (AWG 10...AWG 8) Line side, screw terminal: 4...6 mm ² (AWG 12...AWG 10) Control, screw terminal: 0.5...1.5 mm ² (AWG 20...AWG 16) |
| Type of connector | 1 RJ45 (on the control block) for Modbus serial 2 RJ45 (on the control block) for Ethernet IP/Modbus TCP |
| Physical interface | 2-wire RS 485 for Modbus serial |
| Transmission frame | RTU for Modbus serial |
| Transmission rate | 4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial 10/100 Mbit/s for Ethernet IP/Modbus TCP |
| Exchange mode | Half duplex, full duplex, autonegotiation for Ethernet IP/Modbus TCP |
| Data format | 8 bits, configurable odd, even or no parity for Modbus serial |
| Type of polarization | No impedance for Modbus serial |
| Number of addresses | 1...247 for Modbus serial |
| Method of access | Slave for Modbus TCP |
| Supply | Internal supply for digital inputs and STO: 24 V DC (21...27 V) current \leq 200 mA (overload and short-circuit protection) Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 % current \leq 10 mA (overload and short-circuit protection) External supply for digital inputs: 24 V DC (19...30 V) current \leq 1.25 mA (overload and short-circuit protection) |

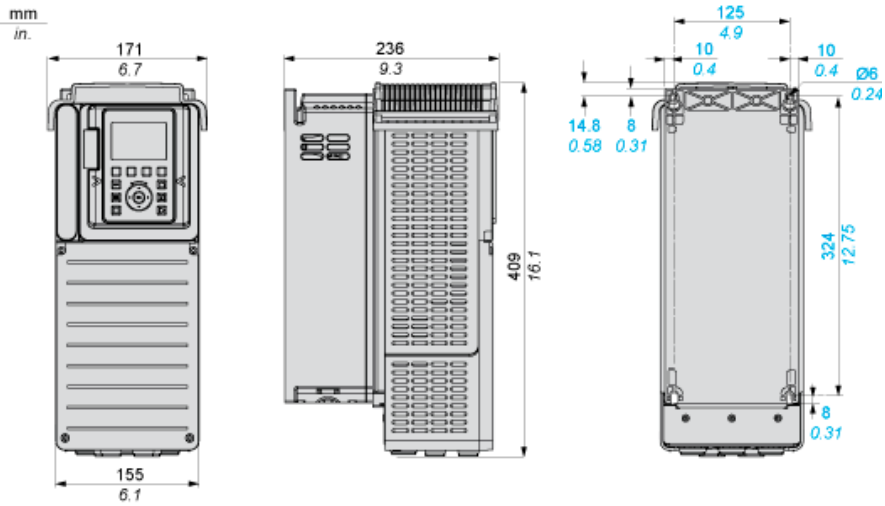
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| Local signalling | 1 LED(s) red for presence of voltage 2 LED(s) dual colour for communication module status 5 LED(s) dual colour for embedded communication status 3 LED(s) mono/dual colour for local diagnostic |
| Width | 171 mm |
| Height | 409 mm |
| Depth | 236 mm |
| Product weight | 7.7 kg |
| Analogue input number | 3 |
| Analogue input type | Software-configurable current AI1, AI2, AI3: 0...20 mA impedance 250 Ohm, resolution 12 bits Software-configurable voltage AI1, AI2, AI3: 0...10 V DC impedance 30 kOhm, resolution 12 bits |
| Discrete input number | 10 |
| Discrete input type | Safe torque off STO A, STOB: 24 V DC (≤ 30 V) impedance > 2.2 kOhm Programmable as pulse input DI7, DI8 0...30 kHz: 24 V DC (≤ 30 V) Programmable DI1...DI8: 24 V DC (≤ 30 V) impedance 3.5 kOhm |
| Input compatibility | Discrete input STOA, STOB : level 1 PLC conforming to EN/IEC 61131-2 Pulse input DI7, DI8 : level 1 PLC conforming to IEC 65A-68 Discrete input DI1...DI8 : level 1 PLC conforming to EN/IEC 61131-2 |
| Discrete input logic | STOA, STOB, positive logic (source): < 5 V (state 0) > 11 V (state 1) DI7, DI8, positive logic (source): < 0.6 V (state 0) > 2.5 V (state 1) DI1...DI8, negative logic (sink): > 16 V (state 0) < 10 V (state 1) DI1...DI8, positive logic (source): < 5 V (state 0) > 11 V (state 1) |
| Analogue output number | 2 |
| Analogue output type | Software-configurable current AQ1, AQ2: 0...20 mA impedance 500 Ohm, resolution 10 bits Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits |
| Discrete output number | 2 |
| Discrete output type | Logic output DQ-: 0...1 kHz (≤ 30 V) DC, < 100 mA Programmable as pulse output DQ+: 0...30 kHz (≤ 30 V) DC, < 20 mA Logic output DQ+: 0...1 kHz (≤ 30 V) DC, < 100 mA |
| Sampling duration | Analog output AQ1, AQ2 : 5 ms (+/- 1 ms) Analog input AI1, AI2, AI3 : 1 ms (+/- 1 ms) Pulse input DI7, DI8 : 5 ms (+/- 1 ms) Discrete input DI1...DI8 : 2 ms (+/- 0.5 ms) |
| Accuracy | Analog output AQ1, AQ2 : +/- 1 % for a temperature variation 60 °C Analog input AI1, AI2, AI3 : +/- 0.6 % for a temperature variation 60 °C |
| Linearity error | Analog output AQ1, AQ2 : +/- 0.2 % Analog input AI1, AI2, AI3 : +/- 0.15 % of maximum value |
| Relay output number | 3 |
| Relay output type | Configurable relay logic R3 : sequence relay NO electrical durability 1000000 cycles Configurable relay logic R2 : sequence relay NO electrical durability 1000000 cycles Configurable relay logic R1 : fault relay NO/NC electrical durability 100000 cycles |
| Refresh time | Relay output R1, R2, R3 : 5 ms (+/- 0.5 ms) |
| Minimum switching current | Relay output R1, R2, R3 : 5 mA at 24 V DC |
| Maximum switching current | Relay output R2, R3 on inductive load ($\cos \phi = 0.4$ and $L/R = 7$ ms) : 2 A at 30 V DC Relay output R2, R3 on inductive load ($\cos \phi = 0.4$ and $L/R = 7$ ms) : 2 A at 250 V AC Relay output R2, R3 on resistive load ($\cos \phi = 1$) : 5 A at 30 V DC Relay output R2, R3 on resistive load ($\cos \phi = 1$) : 5 A at 250 V AC Relay output R1 on inductive load ($\cos \phi = 0.4$ and $L/R = 7$ ms) : 2 A at 30 V DC Relay output R1 on inductive load ($\cos \phi = 0.4$ and $L/R = 7$ ms) : 2 A at 250 V AC Relay output R1 on resistive load ($\cos \phi = 1$) : 3 A at 30 V DC Relay output R1 on resistive load ($\cos \phi = 1$) : 3 A at 250 V AC |
| Isolation | Between power and control terminals |
| IP degree of protection | IP21 |

Environment

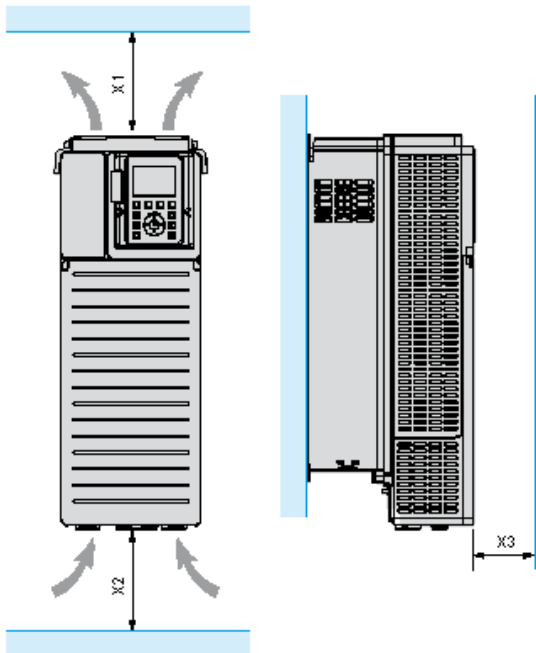
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| Insulation resistance | > 1 mOhm at 500 V DC for 1 minute to earth |
| Noise level | 56 dB conforming to 86/188/EEC |
| Power dissipation in W | 44 W (natural convection) at 380 V switching frequency 4 kHz 172 W (forced convection) at 380 V switching frequency 4 kHz |
| Volume of cooling air | 103 m ³ /h |
| Operating position | Vertical +/- 10 degree |
| THDI | <= 48 % from 80...100 % of load conforming to IEC 61000-3-12 |
| Electromagnetic compatibility | Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 |
| Pollution degree | 2 EN/IEC 61800-5-1 |
| Vibration resistance | 1 gn (f = 13...200 Hz) conforming to IEC 60068-2-6 1.5 mm peak to peak (f = 2...13 Hz) conforming to IEC 60068-2-6 |
| Shock resistance | 15 gn during 11 ms conforming to IEC 60068-2-27 |
| Relative humidity | 5...95 % without condensation conforming to IEC 60068-2-3 |
| Ambient air temperature for operation | 50...60 °C with derating factor -15...50 °C without derating |
| Ambient air temperature for storage | -40...70 °C |
| Operating altitude | 1000...4800 m with current derating 1 % per 100 m <= 1000 m without derating |
| Environmental characteristic | Dust pollution resistance class 3S3 conforming to EN/IEC 60721-3-3 Chemical pollution resistance class 3C3 conforming to EN/IEC 60721-3-3 |
| Standards | IEC 13849-1 IEC 61508 IEC 60721-3 IEC 61000-3-12 EN/IEC 61800-5-1 EN/IEC 61800-3 (environment 2 category C3) EN/IEC 61800-3 (environment 1 category C2) EN/IEC 61800-3 UL 508C |
| Product certifications | CSA TÜV UL REACH |
| Marking | CE |

Dimensions

IP21 / UL Type 1 Drives - Front, Left Side and Rear View



Clearances

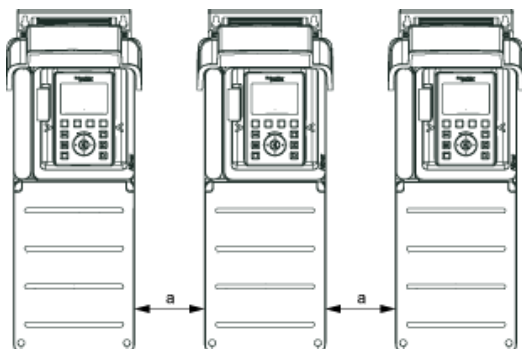


| X1 | X2 | X3 |
|---------------------|---------------------|--------------------|
| ≥ 100 mm (3.94 in.) | ≥ 100 mm (3.94 in.) | ≥ 10 mm (0.39 in.) |

- Mount the device in a vertical position ($\pm 10^\circ$). This is required for cooling the device.
- Do not mount the device close to heat sources.
- Leave sufficient free space so that the air required for cooling purposes can circulate from the bottom to the top of the drive.

Mounting Types

Mounting Type A: Individual IP21



$a \geq 100 \text{ mm (3.94 in.)}$

Mounting Type B: Side by Side IP20

