

MLFB-Ordering data

6SL3210-1KE18-8UF1



Figure similar

Client order no. : Order no. : Offer no. :

Item no.: Consignment no. : Project:

Remarks :			110
Rated d	ata		
Input			
Number of phases	3 AC		
Line voltage	380 480	380 480 V +10 % -20 %	
Line frequency	47 63 Hz	47 63 Hz	
Rated current (LO)	11.40 A		
Rated current (HO)	10.60 A		
Output			
Number of phases	3 AC		
Rated voltage	400V IEC	480V NEC	
Rated power (LO)	4.00 kW	5.00 hp	
Rated power (HO)	3.00 kW	4.00 hp	
Rated current (LO)	8.80 A		
Rated current (HO)	7.30 A		
Rated current (IN)	9.00 A		
Max. output current	14.60 A		
Pulse frequency	4 kHz		
Output frequency for vector control	0 240 Hz		

General tec	in specifications
Power factor λ	0.70 0.85
Offset factor cos φ	0.95
Efficiency η	0.97
Sound pressure level (1m)	52 dB
Power loss	0.15 kW
Filter class (integrated)	Unfiltered
Ambier	nt conditions
Cooling	Air cooling using an integrated fan
Cooling air requirement	0.005 m ³ /s (0.177 ft ³ /s)
Installation altitude	1000 m (3280.84 ft)
Ambient temperature	
Operation	-10 40 °C (14 104 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-40 70 °C (-40 158 °F)
Relative humidity	
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible

General tech. specifications

Overload capability

Output frequency for V/f control

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

0 ... 550 Hz

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

C	losed	-Іоор	control	techniques	

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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Mechanical	data	Con	nmunication
ree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP
ze	FSA	Co	onnections
Net weight	1.70 kg (3.75 lb)	Signal cable	
Width	73 mm (2.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24
Height	196 mm (7.72 in)	Line side	
Depth	208 mm (8.19 in)	Version	Plug-in screw terminals
Inputs / out	tputs	Conductor cross-section	1.00 2.50 mm² (AWG 18
tandard digital inputs		Motor end	
Number	6	Version	Plug-in screw terminals
Switching level: 0→1	11 V	Conductor cross-section	1.00 2.50 mm² (AWG 18
Switching level: 1→0	5 V	DC link (for braking resistor	•)
Max. inrush current	15 mA	Version	Plug-in screw terminals
ail-safe digital inputs		Conductor cross-section	1.00 2.50 mm² (AWG 18
Number	1		
igital outputs		Line length, max.	15 m (49.21 ft)
Number as relay changeover contact	1	PE connection Max. motor cable length	On housing with M4 screw
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)
Number as transistor	1	Unshielded	150 m (492.13 ft)
Output (resistive load)	DC 30 V, 0.5 A		Standards
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)		_,,,,,
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC Directive 2006/95/EC
witching threshold as digital in	put		
0→1	4 V		

PTC/ KTY interface

Analog outputs

1 → 0

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

1.6 V

1 (Non-isolated output)



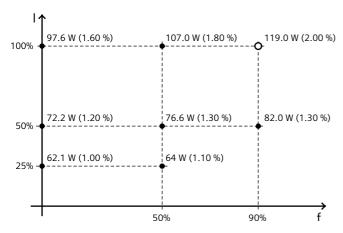
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Figure similar

Converter losses to IEC61800-9-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	32.60 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values