

MLFB-Ordering data

6SL3210-1KE21-7UF1



Client order no. :	
Order no. :	
Offer no. :	

Item no.: Consignment no. : Project :

Remarks :					
Rated data General tech. specification		ch. specifications			
Input			Power factor λ	0.70 0.85	
Number of phases	3 AC		Offset factor cos φ	0.95	
Line voltage	380 480 V +10 % -20 %		Efficiency η	0.97	
Line frequency	47 63 Hz		Sound pressure level (1m)	63 dB	
Rated current (LO)	21.50 A		Power loss	0.24 kW	
Rated current (HO)	18.20 A		Filter class (integrated)	Unfiltered	
Output			Ambier	nt conditions	
Number of phases	3 AC		7 11112121		
Rated voltage	400V IEC	480V NEC	Cooling	Air cooling using an integrated fan	
Rated power (LO)	7.50 kW	10.00 hp	Cooling air requirement	0.009 m³/s (0.318 ft³/s)	
Rated power (HO)	5.50 kW	7.50 hp	Installation altitude	1000 m (3280.84 ft)	
Rated current (LO)	16.50 A		installation attitude	1000 III (3280.84 II)	
Rated current (HO)	12.50 A		Ambient temperature		
Rated current (IN)	17.00 A		Operation	-10 40 °C (14 104 °F)	
Max. output current	25.00 A		Transport	-40 70 °C (-40 158 °F)	
·	4.1.1		Storage	-40 70 °C (-40 158 °F)	
Pulse frequency	4 kHz		Relative humidity		
Output frequency for vector control	0 240 Hz		Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible	
Output frequency for V/f control	0 550 Hz			. 3	
			Closed-loop	control techniques	

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Closed-loop control techniques			
V/f linear / square-law / parameterizable	Yes		
V/f with flux current control (FCC)	Yes		
V/f ECO linear / square-law	Yes		
Sensorless vector control	Yes		
Vector control, with sensor	No		
Encoderless torque control	No		
Torque control, with encoder	No		



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Mechanical data		Communication	
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP
Size	FSB	Connections	
Net weight	2.30 kg (5.07 lb)	Signal cable	
Width	100 mm (3.94 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Height	196 mm (7.72 in)	Line side	
Depth	208 mm (8.19 in)	Version	Plug-in screw terminals
Inputs / out	tputs	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Standard digital inputs		Motor end	
Number	6	Version	Plug-in screw terminals
Switching level: 0→1	11 V	Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Switching level: 1→0	5 V	DC link (for braking resistor)	
Max. inrush current	15 mA	Version	Plug-in screw terminals
Fail-safe digital inputs		Conductor cross-section	4.00 6.00 mm² (AWG 12 AWG 10)
Number	1	Line length, max.	15 m (49.21 ft)
Digital outputs		-	
Number as relay changeover contact	1	PE connection Max. motor cable length	On housing with M4 screw
Output (resistive load)	DC 30 V, 0.5 A		FO (464 04 ft)
•		Shielded	50 m (164.04 ft)
Number as transistor	1	Unshielded	150 m (492.13 ft)
Output (resistive load)	DC 30 V, 0.5 A	Standards	
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)
Number	1 (Differential input)	CE magniting	EMC Directive 2004/108/EC, Low-Voltage
Resolution	10 bit	CE marking	Directive 2006/95/EC
Switching threshold as digital in	put		
0→1	4 V		
1→0	1.6 V		

PTC/ KTY interface

Analog outputs

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^{\circ}\text{C}$

1 (Non-isolated output)



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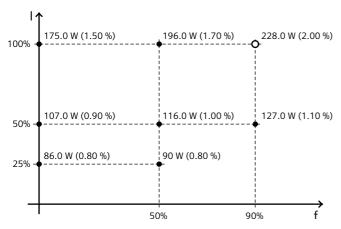
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Figure similar

Converter losses to IEC61800-9-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	36.70 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values